Actuator LA33
With endstop reached and absolute positioning - Analogue feedback





Connection diagram

33XXXXXXXX0AXXXX=XXXXXAXXXXXX

			Power	AMP	Deutsch
		BROWN	2	2	2 FT
		- BLUE	1		
			Signal	AN	
	Supply for feedback	– + RED	2		
	A			Deut 6− <i>Æ</i>	tsch
	Analogue output	– VIOLET	4		-36 50
	Digital output	_ YELLOW	5		_\$0
ا	Digital output	- GREEN	6		
I	Cupply for foodback				
	Supply for feedback	BLACK	1		



If you wish to use the endstop signals, you will have to keep power on the Brown, Blue, Red and Black wires, otherwise the signal will be lost.

The signal power must be turned on at all times when the actuator is running, and minimum one second before it starts to run.

I/O specifications

Input/Output	Specification	Comments		
Description	The actuator can be equipped with an electronic circuit that gives an analogue feedback signal when the actuator moves.			
Brown	12 - 24 V DC (+/-) 12 V ± 20 % 24 V ± 10 %	To extend actuator: Connect Brown to positive To retract actuator: Connect Brown to negative		
Blue	Under normal conditions: 12 V, max. 13 A 24 V, max. 9 A	To extend actuator: Connect Blue to negative To retract actuator: Connect Blue to positive		
Red	Signal power supply (+) 12-24 V DC	Current consumption:		
Black	Signal power supply GND (-)	Max. 60 mA during run and pause There will be accrued a higher inrush current		
Green	Endstop reached out	Output voltage min. V _{IN} - 2 V Source current max. 100 mA NOT potential free		
Yellow	Endstop reached in			
Violet	Analogue feedback 0-10 V 0.5-4.5 V 4-20 mA	Tolerances +/- 0.2 V or mA Transaction delay 20 ms Linear feedback 0.5 % Output: Source Serial resistance: 12 V max 300 ohm 24 V max 900 ohm		
White	Not to be connected			



For actuators with analogue feedback it is recommended to fully extract and retract the actuator on a regular basis (thereby activating the limit switches) in order to ensure precise positioning.

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