Actuator LA36
With absolute positioning Mechanical potentiometer

## **Connection diagram**





## **Connection diagram**

36XXXXXXP00XX-XXXXXXXXXXXXXXX

M		- BROWN	Power 2	AMP	Deutsch
		- BLUE	1		40
	Cumply for foodbook		Signal	AN	1
	Supply for feedback	– + WHITE	3	Deu	
	Analogue output	_ VIOLET	4	6	-1 -1 -20 -20 -20 -20 -20 -20 -20 -20 -20 -20
	Supply for feedback	BLACK	1		

## I/O specifications

Input/Output	Specification	Comments		
Description	The actuator can be equipped with a mechanical potentiometer, 10 k ohm.	Bourns 0-10 k ohm, 5 %, 10-Turn		
Brown	12 V DC ± 20 %, max. 26 A depending on load 24 V DC ± 10 %, max. 13 A depending on load	To extend actuator: Connect Brown to positive To retract actuator: Connect Brown to negative		
Blue	36 V DC ± 10 %, max. 10 A depending on load 48 V DC ± 10 %, max. 8 A depending on load	To extend actuator: Connect Blue to negative To retract actuator: Connect Blue to positive		
Red	Not to be connected			
Black	Signal power supply GND (-)			
Green	Not to be connected			
Yellow	Not to be connected			
	Mechanical potentiometer output  Output range with 8 mm spindle pitch (LA37 only):  1 k ohm = 0 mm stroke  11 k ohm = 333 mm stroke	+10 V or other value		
Violet	Output range with 12 mm spindle pitch:  1 k ohm = 0 mm stroke  11 k ohm = 500 mm stroke	Output protection:  1 k ohm protection resistor in series with the potentiometer  Linearity: ± 0.25%		
	Output range with 20 mm spindle pitch: 1 k ohm = 0 mm stroke 11 k ohm = 833 mm stroke			
White	VCC+ to POT 10 V DC or other values			



Please note that Potentiometer is not possible on variants with fast gear (Spindle pitch 20 mm, H Gear).

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