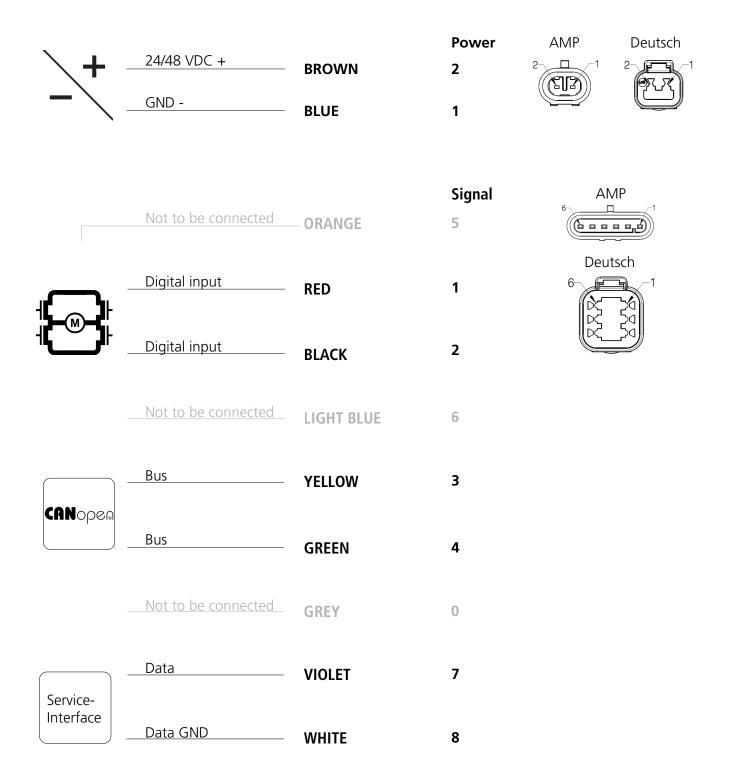
## Actuator LA36 With CANopen 0-point **Connection diagram**





## **Connection diagram**

36XXXXXXX18XX-XXXXXXXXXXXXX



## I/O specifications

Input/Output	Specification				Comments
Description	Compatible with the CiA 301 standard. Using CANopen messages to command movement, setting param-eters and to deliver feedback from the actuator. Actuator support LSS				CANOpen
Brown Connect to positive	12 VDC, current limit 30 A 24 VDC, current limit 20 A 48 VDC, current limit 8 A				Note: Do not swap the power supply polarity on the brown and blue wires! The PCB is coupled to the housing through a capacitor.
	Vsup	Vmin	Vmax		Current limit levels can be adjusted through Actuator Connect <sup>®</sup> . If the temperature drops below 0 °C, all current limits will automatically increase with a factor 2.
	12 V	10,5 V	16 V	Motor running	
		6 V	16 V	Motor not running CAN communication possible	
	24 V	18 V	32 V	Motor running	
		10 V	32 V	Motor not running CAN communication possible	
	48 V	34 V	58 V	Motor running	
		24 V	60 V	Motor not running CAN communication possible	
Blue Connect to negative	- (GND)				
Orange	Not to be used				
Red	Extends the actuator				The signal becomes active at: > 67% of V <sub>IN</sub>
Black	Retracts the actuator				<ul> <li>The signal becomes inactive at:</li> <li>&lt; 33% of V<sub>IN</sub></li> <li>Input current: 10 mA</li> </ul>
Light Blue	Not to be used				Not to be used

Input/Output	Specification	Comments
Green	CAN_L	CANopen assumes a physical layer according to ISO 11898-2. Speed: Autobaud up to 500 kbps Max bus length @ 125 kbps: 500 meters Max bus length @ 250 kbps: 250 meters
Yellow	CAN_H	Max bus length @ 500 kbps: 100 meters Max stub length @ 125 kbps: 22 meters Max stub length @ 250 kbps: 11 meters Max stub length @ 500 kbps: 5,5 meters Max node count: 127 Wiring: Unshielded twisted pair
Violet	Service interface	Only Actuator Connect <sup>®</sup> can be used as service interface.
White	Service interface GND	Use grey adapter cable

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