	RING SERVICE						CONNECTION
VIEW	Current Configuration	Parameter			Value		Overview
JAL LIMITS	Virtual Limit Inwards	Parameter		0 mm	Vaue		onfigurable parameters. Double-click
ALC LIVITIS	Virtual Limit Outwards			0 mm			arameter you wish to change.
ENT LIMITS	Current Limit Inwards			20,09 A			
	Current Limit Outwards			20,09 A 100 %		T	he Unapplied changes will appear u
>	Maximum Speed Soft Stop Inwards			100 % 1000 ms		- C	hanges are applied.
STOP	Soft Stop Outwards			1000 ms		P	ress Revert to cancel unapplied chan
	Soft Start Inwards			1000 ms			
START	Soft Start Outwards			1000 ms			
	Number of actuators			2			
r	Unapplied Changes						
[	Unapplied Changes	neter		Current Value	New Value	•	
		neter	_	Current Value	New Volue	•	
		neter	_	Current Value	New Value		
		nder	_	Current Value	New Value	•	
		nder	_	Current Value	New Value	•	
		nder	_	Correct Value	New Value	•	
		neter	_	Current Value	New Value	•	
		nder	_	Correct Value	New Value	0	
		nder		Corrent Value	New Value	0	
			Appy Reest	Current Value	New Value	0	
Run b	Parat		Apply Rovert	Current Value	New Yalus	0	CFG Nume: 1099/90/0000
	Parat Sep h Kuris		Royly Rowst	Corrent Value	New Value	0	916 Name: 1999/96/0500 815 AM



# BusLink software Data sheet



# BusLink - Software

Actuators with IC - Integrated Controller<sup>™</sup> from LINAK<sup>®</sup> can be configured via the BusLink software.

When using the BusLink software you can easily adjust parameters like e.g. soft start/stop, virtual limits and current limits. In the service tab you will find historic usage data, which can be used to analyse the performance of both the actuators and the application where it is installed.



#### Features:

BusLink is divided into three areas:

- Configure Virtual limits, current limits, speed, soft start/stop and feedback (also possible to add/remove an actuator from a parallel system)
- Monitoring Real-time graph showing current, position and supply voltage
- Service Historical data which can be exported as a PDF file for review

#### Options in general:

• Can be used for IC (Advanced and Parallel), CAN Bus, LINBus and Modbus actuators

#### Usage:

• The BusLink software is only compatible with Microsoft Windows operating systems

## Getting started with BusLink

The BusLink software is free and available for download here:

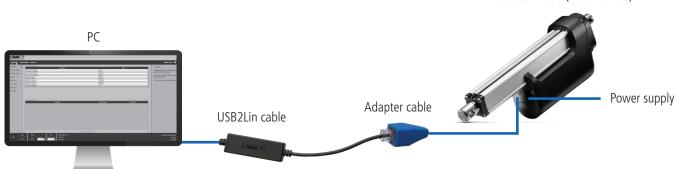


### A BusLink cable kit is required to connect the actuator to a PC:

The kit contains 1 x USB2Lin interface cable and 1 x adapter cable

	LA12/LA25 IC	LA33/LA36/LA37	LA36/LA37 Modbus	LA33/LA36/LA37 CAN Bus	LA14/LA25 CAN Bus
	<i>Blue interface</i>	<i>Blue interface</i>	Yellow interface	Green interface	Green interface
Ordering no.	0147999	0367999	0367998	0367997	0147997

# System example:





### Quick guide

Are you looking for a guide on how to use **BusLink** for your actuator?

https://linak.as/2mcgz0L

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